ANOMALY DETECTION IN MANUFACTURING SYSTEMS BASED ON DIGITAL TWIN AND MACHINE LEARNING

JOURNÉES DE LA SAGIP – CT IMS² (INTELLIGENT MANUFACTURING & SERVICES SYSTEMS)

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DIGITAL TWIN PARADIGM

- (Liu et al., 2018) describe DT as "a living model that continually adapts to change in the environment or operation using real-time data and can forecast the future of the corresponding physical asset's behavior"
- According to (Kaur et al., 2020), a digital twin's main feature is its ability to correctly replicate physical space using a combination of physics-based and data-driven models
- DT can check the consistency of monitored data, perform data mining to detect existing and forecast upcoming problems, using Artificial Intelligence to support effective decisions. (Asimov et al., 2018).

Liu, Zheng, Norbert Meyendorf, et Nezih Mrad. 2018. « The role of data fusion in predictive maintenance using digital twin ». AIP Conference Proceedings 1949

Kaur, Maninder Jeet, Ved P. Mishra, et Piyush Maheshwari. 2020. « The Convergence of Digital Twin, IoT, and Machine Learning: Transforming Data into Action ». In Digital Twin Technologies and Smart Cities

Asimov, R., S Chernoshey, Ingmar Kruse, et Vital Asipovich. 2018. DIGITAL TWIN IN THE ANALYSIS OF A BIG DATA

DIGITAL TWIN SERVICES

Considering the nine services listed by (Tao et al., 2018), they can be grouped in these categories:

- Real-time state monitoring;
- Energy consumption analysis;
- Failure analysis and prediction, and maintenance strategy;
- Intelligent optimization and update;
- User behavior analysis and user operation guide;
- Product virtual maintenance and product virtual operations;

MONITORING DEFINITION FROM PHM POV

- According to (Saez et al. 2020), Process monitoring aims to :
 - Demonstrate the current status of the system;
 - Show undesired or unallowed deviations from the acceptable behavior → Fault/ anomaly !!
- Necessity to detect and diagnose these faults
 → potential premature failure
- Fault/ anomaly detection and diagnosis scheme:
 - **Detection**: Detect malfunctions in real-time
 - **Isolation**: Isolate the component to find the root cause
 - **Identification**: Estimate the size and type of the fault

Model based

Verify the consistency between observations and expected system behavior

i.e. Observers, Kalman filter, parity equations...etc.

Data driven

Learn the system behavior pattern based on historical data

i.e. ANN, PCA, SVM, RF...etc.

Knowledge based

The assessment of online monitored data according to a set of rules specified by

expert knowledge

i.e. Expert system, Fuzzy logic

LITERATURE REVIEW



LITERATURE REVIEW RESULTS

Overall findings

DT can be used to:

- I) Generate synthetic data
- 2) Track the machinery degradation process
- 3) Monitor production process
- 4) Improve the decision-making process in maintenance
- 5) Support production issues after abnormality: rescheduling, energy-saving...etc.

The hybrid approach is better to overcome the drawbacks of each method \rightarrow DT is often combined with Data-driven methods

Artificial intelligence methods are widely used, especially Deep learning

Research gap

Fault detection and diagnosis at the machine or component level \rightarrow less common on the system level

Lack of interest to behavioral anomalies

Lack of design methodology, reliability, and verification of the DT



APPLICATION CHALLENGES

The reliability of the model



RELIABILITY OF THE MODEL

Phase 0: offline



RELIABILITY OF THE MODEL

Phase 0: offline



RELIABILITY OF THE MODEL

Phase I: online



ASSEMBLY LINE



METHODOLOGY



DATA PREPROCESSING

Encoding









ANOMALY DETECTION

- Identifies any potential deviation from normal operation
- Unsupervised learning
 - ✓ Isolation Forest
 - Local Outlier Factor
 - OneClassSVM





PIPELINE DEPLOYMENT



EXPERIMENTAL SETUP





Objective

Apply a series of different type and level of severity of disturbances and observe the ability of the system to detect faults

PRELIMINARY STUDIES



VALIDATION

- 3 experiments :
 - \circ Low disturbances
 - High disturbances
 - Mixed disturbances
- Simulation horizon per replica =4 hours
- N replicas = 5 per experiment
- Various faults at time
- Type of faults
 - Minor stoppages ==> 6 workstations
 - Speed loss==> conveyors



CONCLUSION

- The combination of methods (Model-based and data-driven) as a hybrid method to monitor, detect and diagnose behavioral anomalies in Manufacturing systems
- Reduce performance losses (Minor stoppages and speed losses) through the used method
- Experimental demonstration of the proposed framework
- Reliability of the DT model to assess the nominal behavior of the physical system
- Subtle challenge of training an accurate AI model
- Online training/updating of the model is considered in future work

THANK YOU FOR YOUR ATTENTION !

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